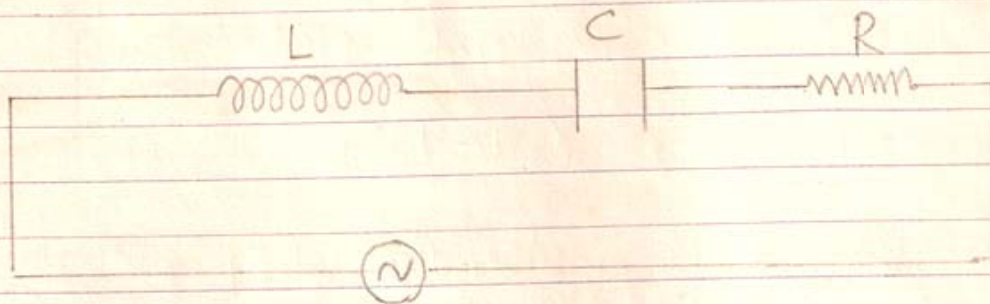




L-C-R circuit:



An alternating source of e.m.f is connected across an L-C-R circuit.

Given:

L = self inductance of the coil.

C = the capacitance of the capacitor.

R = the resistance in the circuit.

$e = E_p \sin \omega t$  — (1) the instantaneous e.m.f applied across the circuit.

We first solve the circuit by e.m.f eq<sup>n</sup> method:

Let Q be the charge stored in the capacitor at the instant of time t.

i be the current flowing in the circuit at the instant of time 't'.

The e.m.f eq<sup>n</sup> of the circuit at the instant of time 't':

$$L \frac{di}{dt} + iR + \frac{Q}{C} = e = E_p \sin \omega t$$

Differentiating w.r to t:

$$L \frac{d^2i}{dt^2} + R \frac{di}{dt} + \frac{1}{C} \frac{dQ}{dt} = \omega E_p \cos \omega t$$

Putting  $\frac{dQ}{dt} =$

## AC through L-C-R Circuit



$$\therefore L \frac{d^2 i}{dt^2} + R \frac{di}{dt} + \frac{i}{C} = \omega E_p \cos \omega t \quad \text{--- (2)}$$

Let us assume a trial solution of eq<sup>n</sup> (2) :-

$$i = I_p \sin(\omega t - \phi) \quad \text{--- (3) where } I_p \text{ \& } \phi \text{ are unknown.}$$

Since eq<sup>n</sup> (3) is a solution of eq<sup>n</sup> (2) it must satisfy eq<sup>n</sup> (2) putting eq<sup>n</sup> (3) in (2) :

$$L \cdot \omega^2 I_p \left\{ -\sin(\omega t - \phi) \right\} + R \omega I_p \cos(\omega t - \phi) + \frac{I_p}{C} \sin(\omega t - \phi) = \omega E_p \cos \omega t$$

$$I_p \omega \left[ R \cos(\omega t - \phi) - \left( \omega L - \frac{1}{\omega C} \right) \sin(\omega t - \phi) \right] = \omega E_p \cos \omega t$$

$$\propto I_p \left[ \cos \omega t \left\{ R \cos \phi + \left( \omega L - \frac{1}{\omega C} \right) \sin \phi \right\} + \sin \omega t \left\{ R \sin \phi - \left( \omega L - \frac{1}{\omega C} \right) \cos \phi \right\} \right] = E_p \cos \omega t \quad \text{--- (4)}$$

Equating the coeff. of  $\sin \omega t$  term both sides of eq<sup>n</sup> (4) :

$$I_p \left\{ R \sin \phi - \left( \omega L - \frac{1}{\omega C} \right) \cos \phi \right\} = 0$$

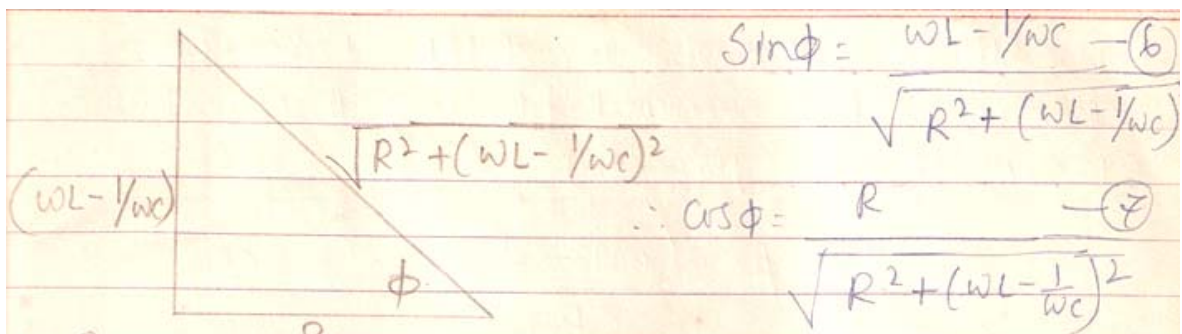
$$\text{But } I_p \neq 0 \quad \therefore R \sin \phi = \left( \omega L - \frac{1}{\omega C} \right) \cos \phi$$

$$\propto \tan \phi = \frac{\left( \omega L - \frac{1}{\omega C} \right)}{R} \quad \text{--- (5)}$$

from (5) the unknown ' $\phi$ ' can be calculated.



## AC through L-C-R Circuit



Equating the coeff. of  $\cos \omega t$  from both sides:

$$I_p = \frac{E_p}{R \cos \phi + (\omega L - \frac{1}{\omega c}) \sin \phi}$$

Putting eq<sup>ns</sup> (6) & (7):

$$I_p = \frac{E_p}{\frac{R \cdot R}{\sqrt{R^2 + (\omega L - \frac{1}{\omega c})^2}} + \frac{(\omega L - \frac{1}{\omega c})(\omega L - \frac{1}{\omega c})}{\sqrt{R^2 + (\omega L - \frac{1}{\omega c})^2}}}$$

$$\text{or } I_p = \frac{E_p \sqrt{R^2 + (\omega L - \frac{1}{\omega c})^2}}{R^2 + (\omega L - \frac{1}{\omega c})^2}$$

$$\text{or } I_p = \frac{E_p}{\sqrt{R^2 + (\omega L - \frac{1}{\omega c})^2}} \quad \text{--- (8)}$$

From eq<sup>n</sup>. (8) we find that the total resistance offered by the L-C-R circuit to the flow of A.C is the impedance of the circuit

$$Z = \frac{E_p}{I_p} = \sqrt{R^2 + (\omega L - \frac{1}{\omega c})^2} = \sqrt{R^2 + (X_L - X_C)^2} \quad \text{--- (9)}$$



Phase difference between the total P.d across the circuit & the current flowing through the circuit is ' $\phi$ ' given by

$$\tan \phi = \frac{(\omega L - \frac{1}{\omega c})}{R} \quad \text{--- (5)}$$

Discussions: For the given values of  $L, C \& \omega$  we have three different possibilities.

Case I:

$$\omega L > \frac{1}{\omega c} \quad \text{i.e.} \quad X_L > X_c \quad \text{or} \quad \omega > \frac{1}{\sqrt{LC}}$$

From (5)  $\tan \phi = +ve$  i.e.  $\phi$  is +ve. In this case the P.d across the circuit leads the current by phase angle ' $\phi$ '.

Case II:  $\omega L < \frac{1}{\omega c}$  i.e.  $X_L < X_c$  or  $\omega < \frac{1}{\sqrt{LC}}$

From eq<sup>n</sup> (5)  $\tan \phi = -ve$  i.e.  $\phi$  is negative. In this case the total P.d across the circuit lags the current by phase angle ' $\phi$ '.

Case III  $\omega L = \frac{1}{\omega c}$  i.e.  $X_L = X_c$  or  $\omega = \frac{1}{\sqrt{LC}}$

From (5);  $\tan \phi = 0$  i.e.  $\phi = 0$ . In this case the P.d across the circuit is in phase with the current i.e. circuit behaves as a purely resistive circuit.

The impedance of the circuit  $Z = \sqrt{R^2 + 0^2}$   
 $Z = R = \text{Pure resistance.}$

In this case the impedance of the circuit is



## AC through L-C-R Circuit

minimum & hence current flowing through the circuit is  $\text{max}^m$  and therefore the circuit is said to be in resonance. (current means r.m.s current).

$$\text{The frequency } 2\pi f = \frac{1}{\sqrt{LC}}$$

$$f = \frac{1}{2\pi} \sqrt{\frac{1}{LC}}$$

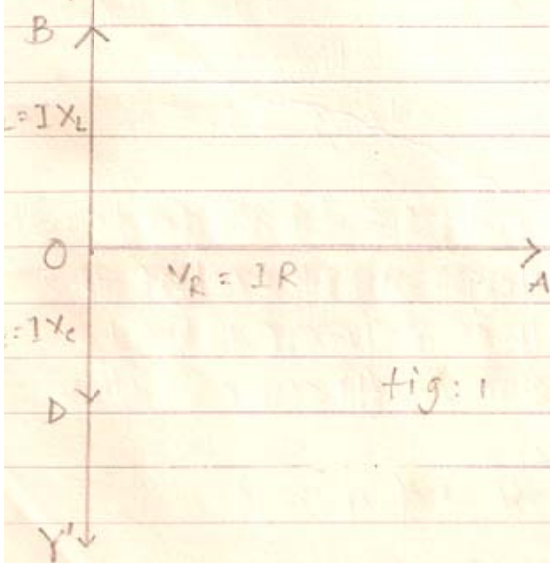
This frequency is known as resonant frequency

$$\omega_r = \frac{1}{\sqrt{LC}} \quad \text{or } 2\pi f_r = \frac{1}{\sqrt{LC}} \quad \text{or } f_r = \frac{1}{2\pi} \sqrt{\frac{1}{LC}}$$

[This is an example of electrical forced vibration].

Vector diagram:

(i) Let the direction of  $\vec{OX}$  represent the phase of current flowing through the circuit.



(ii) The P.D across the resistance  $V_R = IR$  being in phase with current can be represented

by a vector  $\vec{OA}$  having length  $OA = IR$  & the direction along  $OX$ .

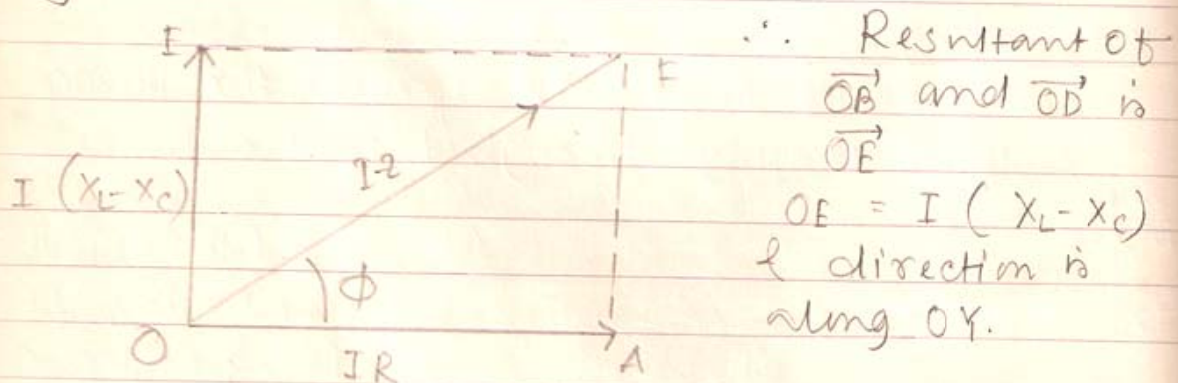


## AC through L-C-R Circuit

(iii) The P.D across the inductance  $V_L = I X_L$  leads the current, by phase angle  $\pi/2$  & hence can be represented by a vector  $\vec{OB}$  having length  $OB = I X_L$  and direction along  $Y$ -axis.

(iv) P.D across the Capacitor  $V_C = I X_C$  lags the current by phase angle  $\pi/2$  & hence can be represented by a vector  $\vec{OD}$ ; having length  $OD = I X_C$  & direction along  $OY'$   
Let  $X_L > X_C \therefore V_L > V_C$  i.e.  $OB > OD$

$\vec{OB}$  and  $\vec{OD}$  being along the same line in opposite directions, the resultant of the two vectors will be the difference of the magnitude of the two vectors, towards the greater vector.



The resultant of  $\vec{OA}$  and  $\vec{OE}$  can be found by the law of parallelogram of vectors the diagonal  $\vec{OF}$  represent the value of total P.D as well as the phase difference with current.

$$OF^2 = OA^2 + AE^2 = I^2 R^2 + I^2 (X_L - X_C)^2$$



$$\text{or } OF = I \sqrt{R^2 + (X_L - X_C)^2} \quad \text{--- (1)}$$

Let  $Z$  be the impedance of the circuit  
 Total P.D across the circuit  $V = IZ = OF$  --- (2)

$$\therefore IZ = I \sqrt{R^2 + (X_L - X_C)^2}$$

$$Z = \sqrt{R^2 + (X_L - X_C)^2} \quad \text{--- (3)}$$

from  $\Delta AOF$ ;  $\cos \phi = \frac{OA}{OF} = \frac{IR}{IZ} = \frac{R}{\sqrt{R^2 + (X_L - X_C)^2}}$

In this case if  $X_L > X_C$  from the diagram we find that the total P.D across the circuit leads the current by phase angle ' $\phi$ '

from  $\Delta AOF$ ;  $\tan \phi = \frac{AF}{OA} = \frac{X_L - X_C}{R}$

$$\tan \phi = \frac{(\omega L - \frac{1}{\omega C})}{R}$$

J- Operator method:

- (i) Since the P.D across the resistance  $V_R = IR$  is in phase with current; it can be vectorially represented as  $\vec{V}_R = \vec{I}R$
- (ii) P.D across inductance  $V_L = IX_L$  leads the current by phase angle  $\pi/2$  and can be vectorially represented as  $\vec{V}_L = j\vec{I}X_L$
- (iii) P.D across the capacitor  $V_C = IX_C$  lags the current, by phase angle  $\pi/2$  and can be vectorially represented as  $\vec{V}_C = -j\vec{I}X_C$ .



## AC through L-C-R Circuit

$\therefore$  The total P.D across the circuit can vectorially be represented as  $\vec{V} = \vec{V}_R + \vec{V}_L + \vec{V}_C$

$$\text{or } \vec{V} = \vec{I} [R + j(X_L - X_C)] \text{ --- (1)}$$

Let  $z^* = z e^{j\phi}$  be the complex vector impedance of the circuit.

$\therefore$  The total P.D across the circuit

$$\vec{V} = \vec{I} z^* = \vec{I} z e^{j\phi} \text{ --- (2)}$$

Where  $z$  = magnitude of the impedance

&  $\phi$  = Phase difference between the P.D & the current.

Equating (1) and (2) :-

$$\vec{I} z [\cos\phi + j\sin\phi] = \vec{I} [R + j(X_L - X_C)]$$

Equating real and imaginary parts :

$$z \cos\phi = R \text{ --- (3)}$$

$$z \sin\phi = (X_L - X_C) \text{ --- (4)}$$

$\therefore$  Squaring and adding (3) and (4) :

$$z = \sqrt{R^2 + (X_L - X_C)^2} \text{ --- (5)}$$

Dividing eq<sup>n</sup> (4) by (3) ;

$$\tan\phi = \frac{X_L - X_C}{R} = \frac{\omega L - 1/\omega C}{R}$$

The P.D across the circuit may lead or lag the current depending on the values of  $\omega$ ,  $L$  &  $C$ .  
From eq<sup>n</sup> (3), the power factor of the circuit is

$$\cos\phi = \frac{R}{z}$$